

# Design of a Low-Power Potentiostatic Second-Order CT Delta-Sigma ADC for Electrochemical Sensors

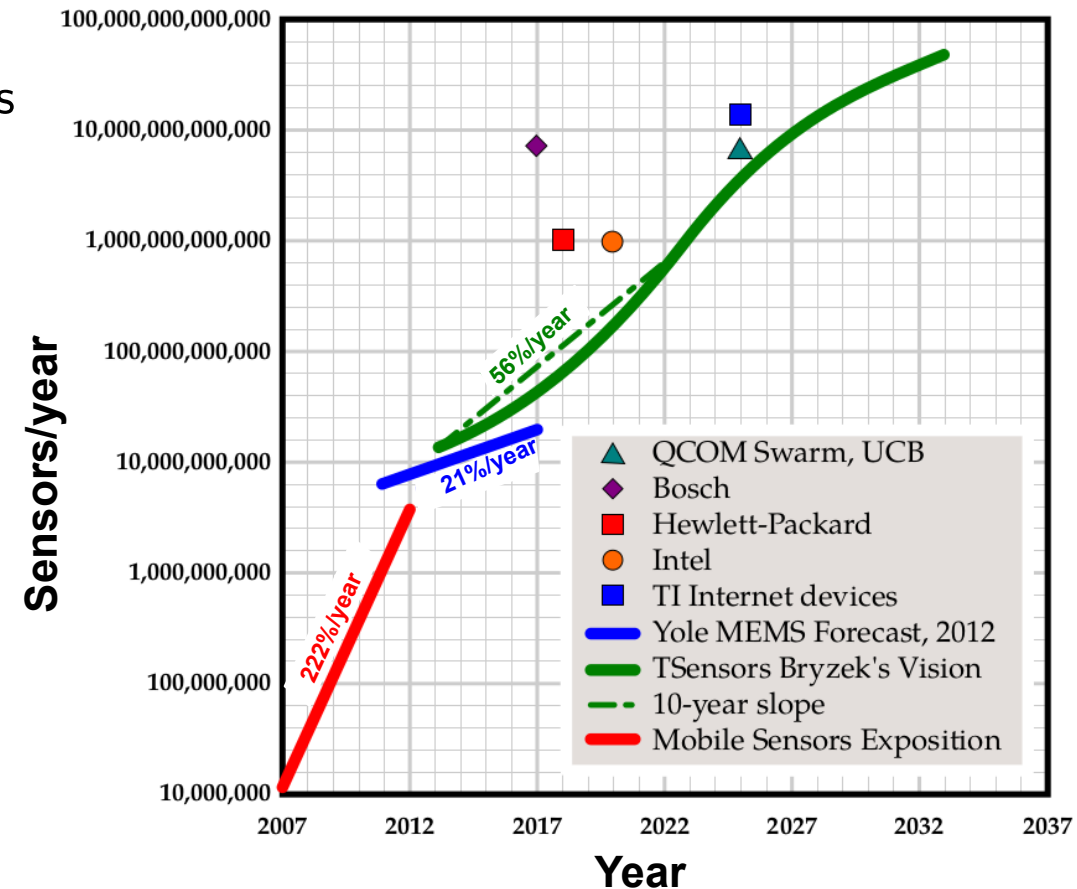
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## Trillion-Sensor Vision

- ▶ Several organizations created visions for continued growth to trillion(s) sensors
  - \$15 trillion by 2022
- ▶ **Electrochemical sensors** are growing exponentially due to potential of miniaturization and mass production
  - **Monolithic** or **hybrid** integration onto CMOS platforms
  - Applications in biosensors, quality control, ...



Expected sensor production growth per year

[www.tsensorssummit.org](http://www.tsensorssummit.org)

- 1 Amperometric Electrochemical Sensors
- 2 Potentiostatic  $\Delta\Sigma$  Modulator architecture
- 3 Proposed architecture
- 4 Design methodology and trade-offs
- 5 Conclusions

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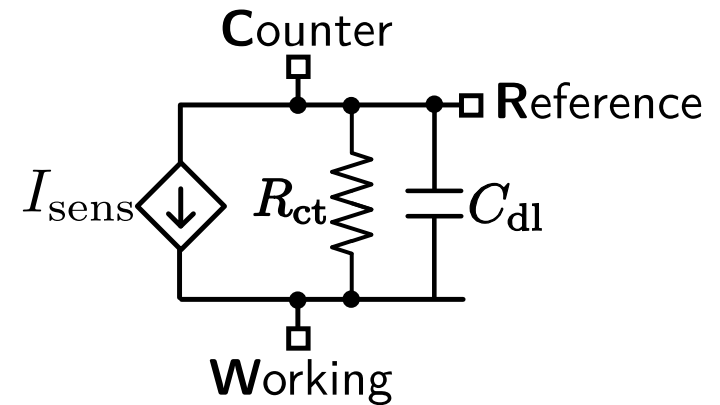
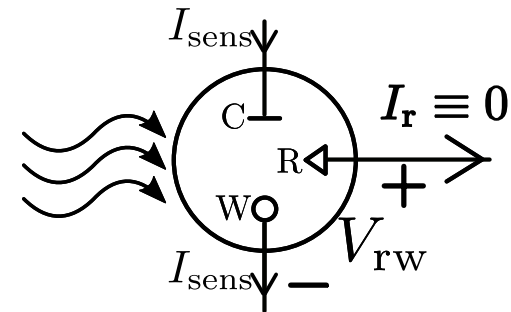
# Amperometric Electrochemical Sensors

- ▲ Interaction with microorganisms
- ▲ **Selectivity** by functionalization
- ▼ Reduced **speed** and **life** time
- ▼ **Potentiostatic** and **amperometric** operations

► **Three electrodes:**

- Working
- Reference
- Counter

- Measurement independent of the **R** and **C** impedances.



- Electrochemical **time constant**:  

$$\tau_{ch} = R_{ct} C_{dl} \approx 10^{-1} \text{ s}$$
**R<sub>ct</sub>** = charge-transfer resistance  
**C<sub>dl</sub>** = double-layer capacitance

## Classic circuit implementation

### ► Potentiostat

- $A_1$  establishes the control loop to accomplish potentiostat operation

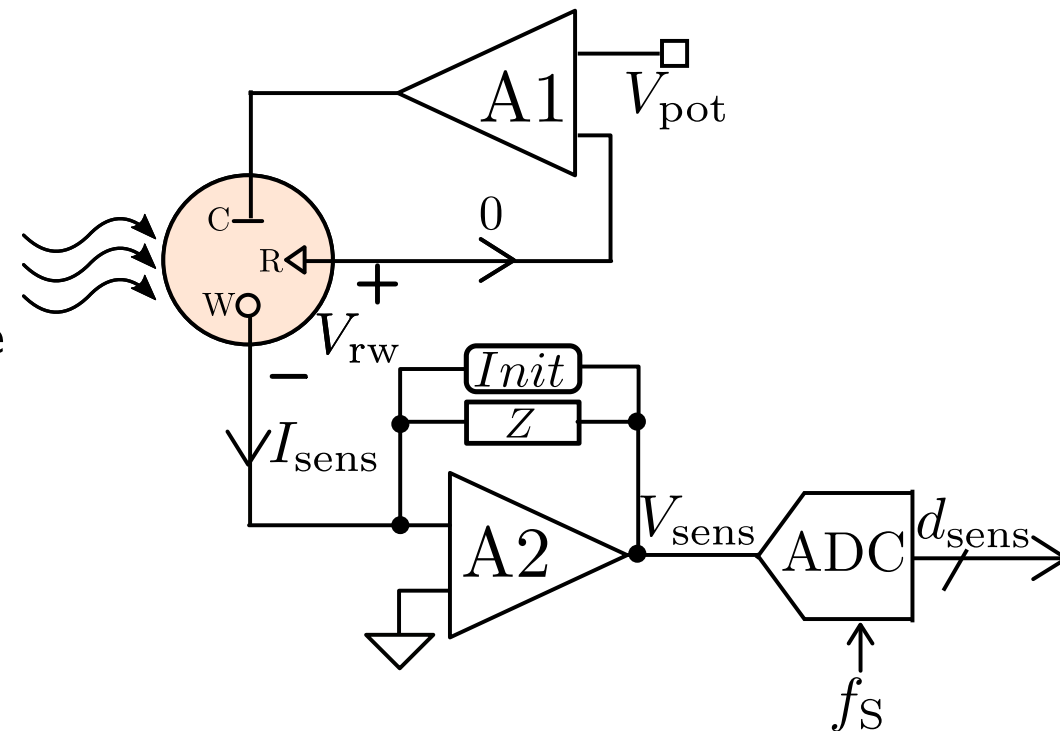
$$V_{rw} = V_{pot} \quad \& \quad I_r \equiv 0$$

### ► Amperometry

- $A_2$  converts sensor current to voltage for digitization and readout

▼ Requires multiples OpAmps + ADC

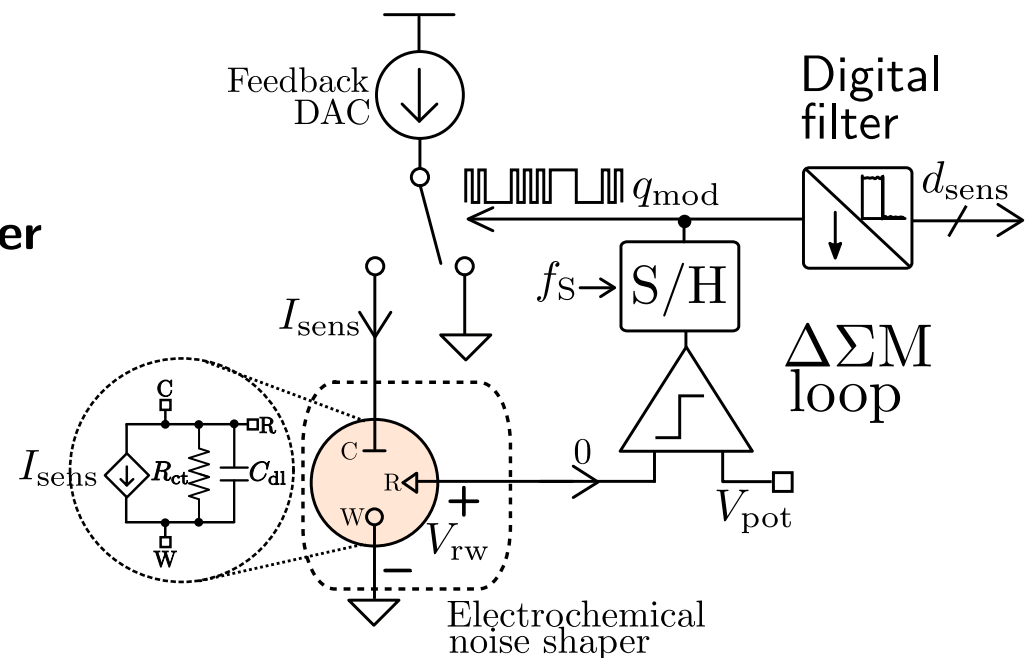
▼ Large area and power consumption



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## Potentiostatic $\Delta\Sigma$

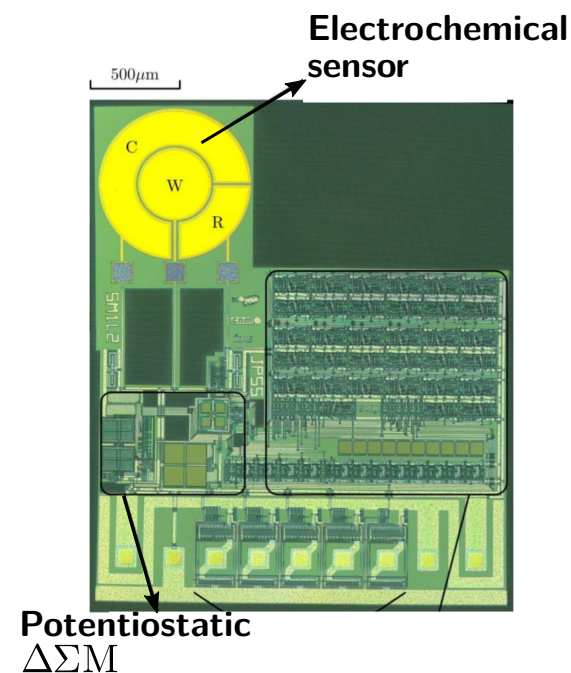
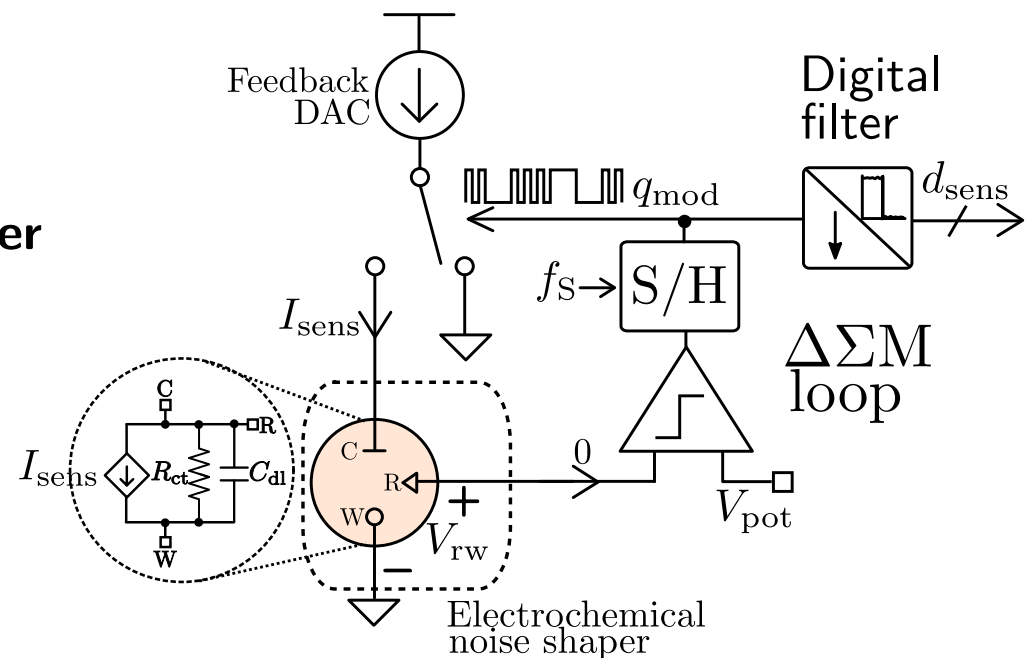
- ▶ Behaviour similar to **low-pass first-order single-bit CT  $\Sigma\Delta$  A/D modulator**
- ▶ Error current converted into voltage and shaped in frequency by the **electrochemical sensor** itself
- ▲ High oversampling ratios (**OSR > 100**) can be easily obtained with kHz-range clock frequencies  $f_s$
- ▲ **Amperometric** read-out through the  $\Delta\Sigma$  modulation of output bit stream  $q_{\text{mod}}$  by chemical input  $I_{\text{sens}}$





## Potentiostatic $\Delta\Sigma M$

- ▶ Behaviour similar to **low-pass first-order single-bit CT  $\Sigma\Delta M$**  A/D modulator
- ▶ Error current converted into voltage and shaped in frequency by the **electrochemical sensor** itself
- ▶ High oversampling ratios (**OSR > 100**) can be easily obtained with kHz-range clock frequencies  $f_s$
- ▶ **Amperometric** read-out through the  $\Delta\Sigma$  modulation of output bit stream  $q_{mod}$  by chemical input  $I_{sens}$
- ▶ **Monolithic CMOS integration**  
Inexpensive  $2.5\mu m$  in-house CMOS technology (CNM25) developed by ICAS group at IMB-CNM(CSIC)



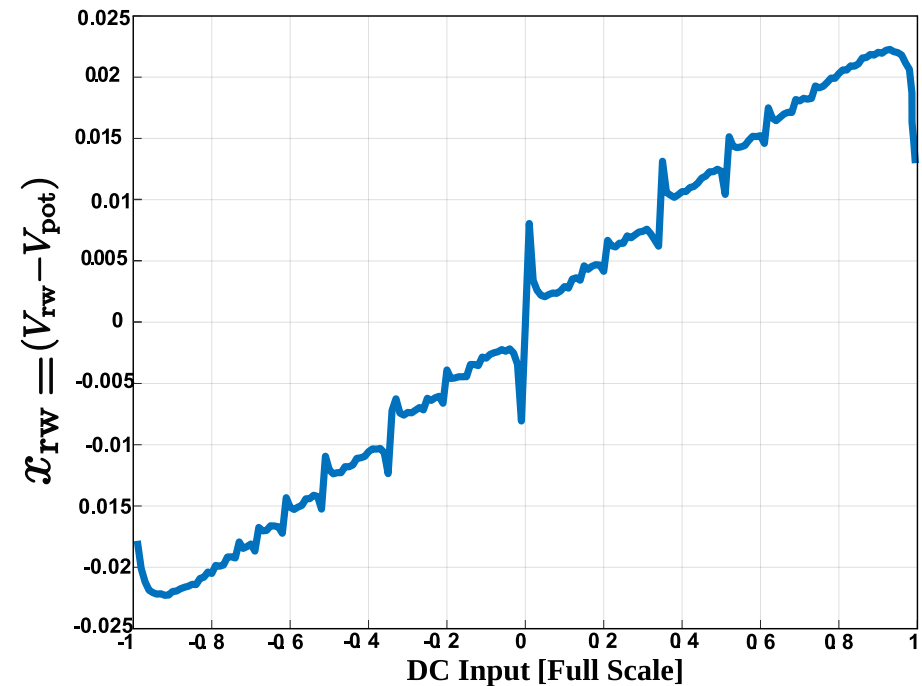
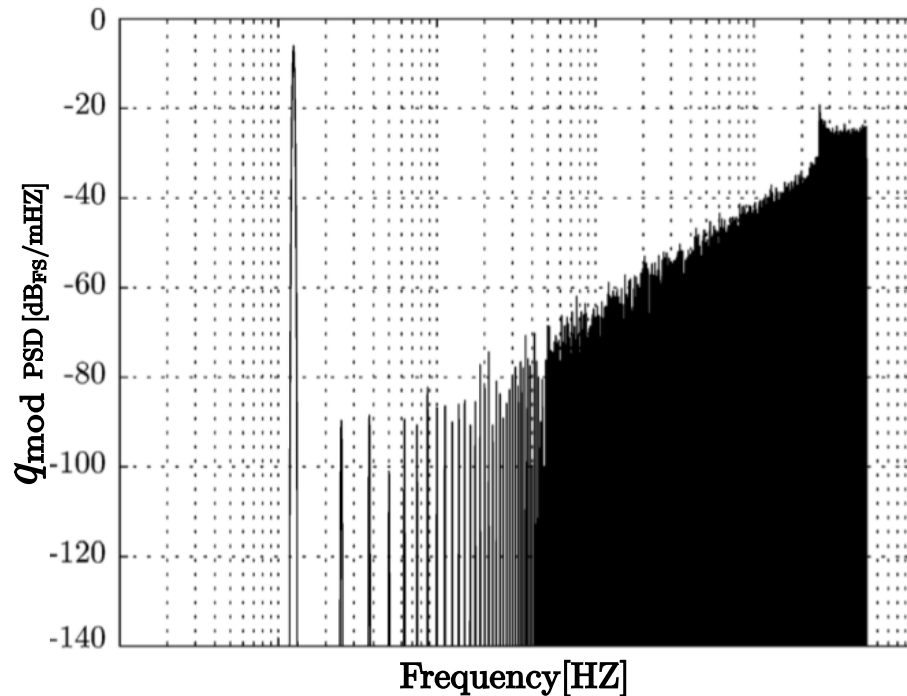
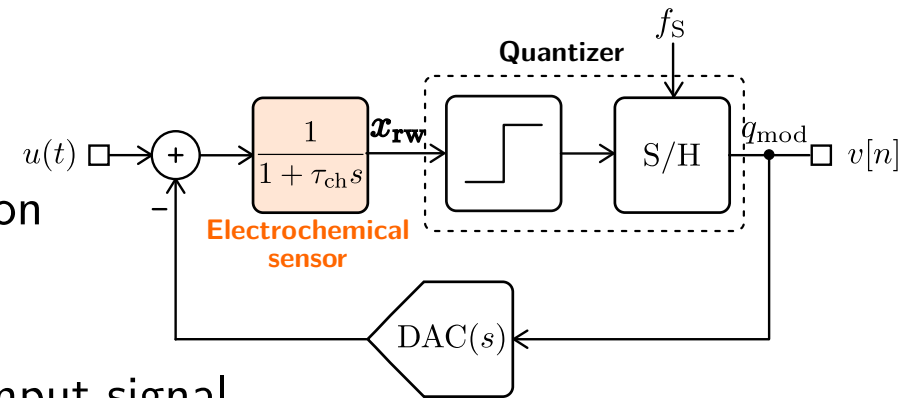
# Potentiostatic ΔΣM

▼ Typical **tonal component** of 1<sup>st</sup> order ΔΣM

■ Quantization error and input signal correlation

▼ **Potentiostat operation** not well-defined

■ Potentiostatic error  $x_{rw}$  influenced by the input signal

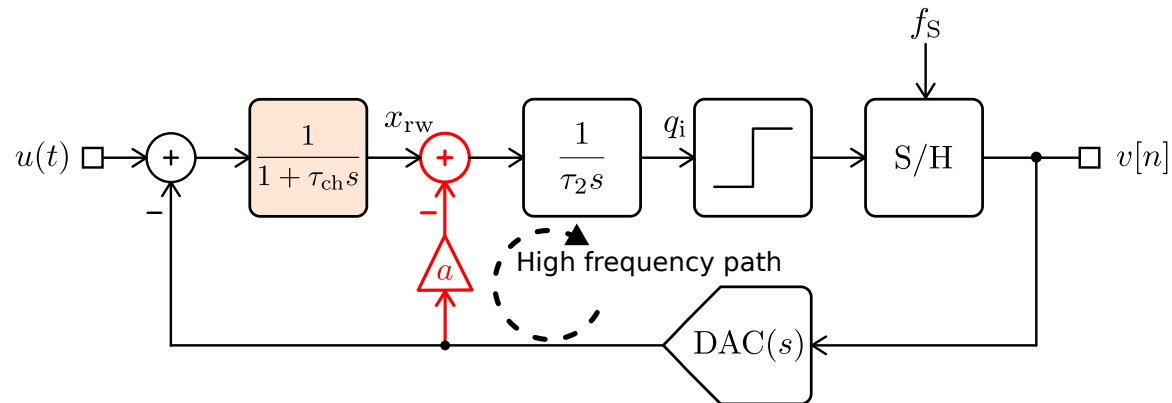


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## Stability compensation

### ► Distributed FeedBack Topology

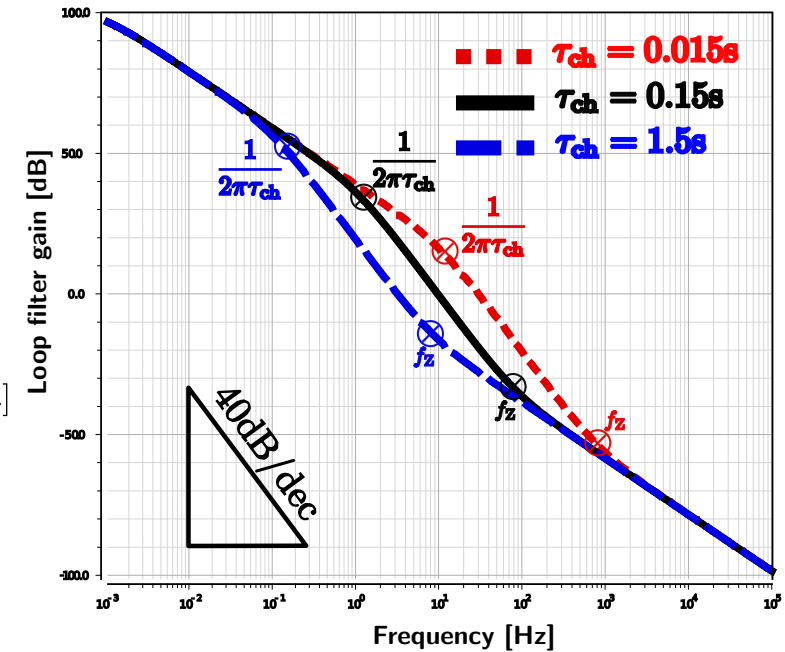
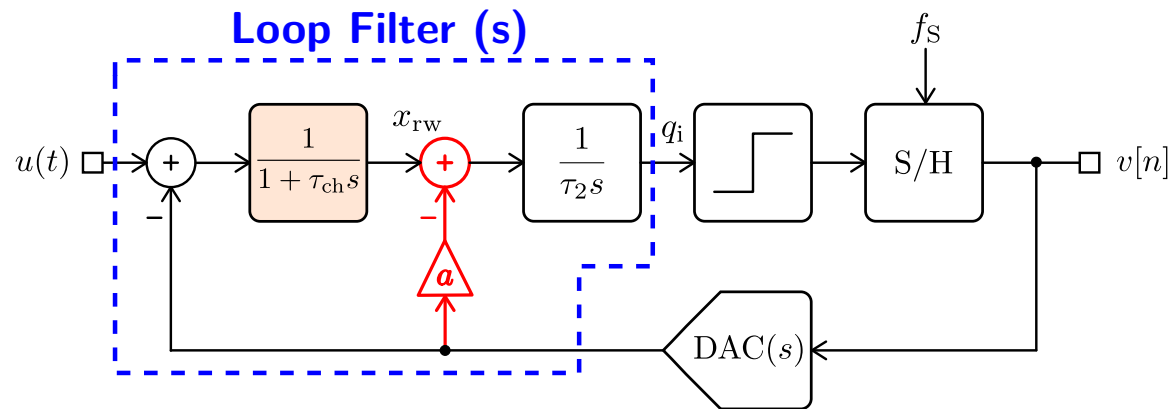


### ► Loop Filter Zero frequency location

$$H_{\text{FB}}(s) \approx \frac{1 + \frac{a}{1+a} \tau_{\text{ch}} s}{(1 + \tau_{\text{ch}} s) \tau_2 s} ; \quad f_Z = \frac{1 + a}{2\pi a \tau_{\text{ch}}}$$

# Stability compensation

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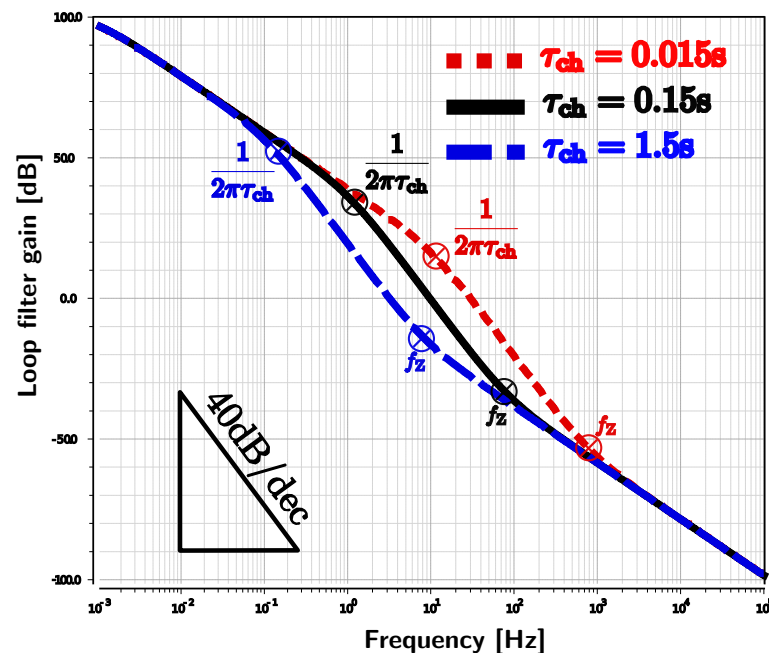
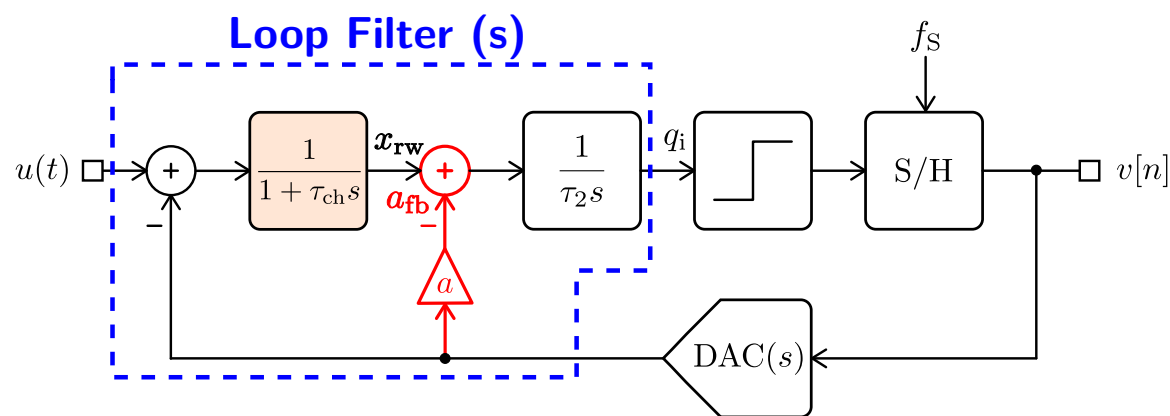
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- ▼  $f_z$  depends on sensor time constant  $\tau_{ch}$
- $\downarrow \tau_{ch} \rightarrow \uparrow f_z$  Leading to instability!!

# Stability compensation

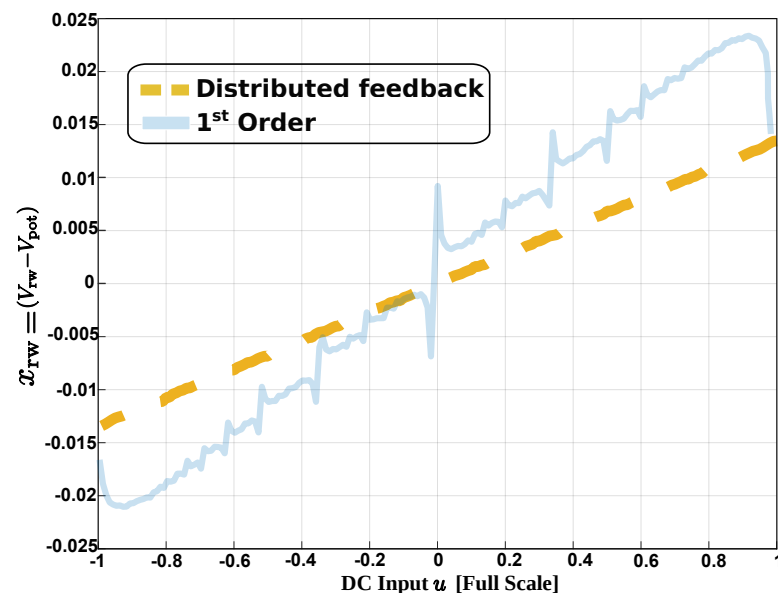
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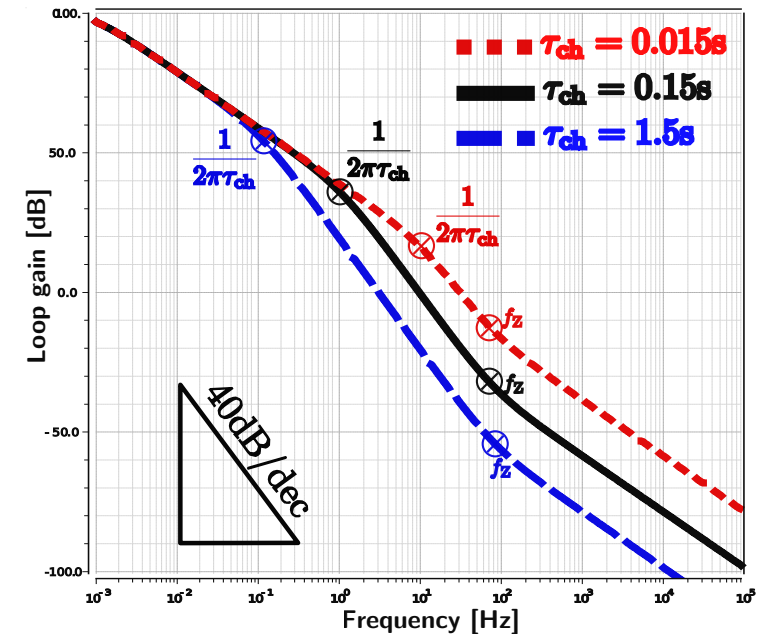
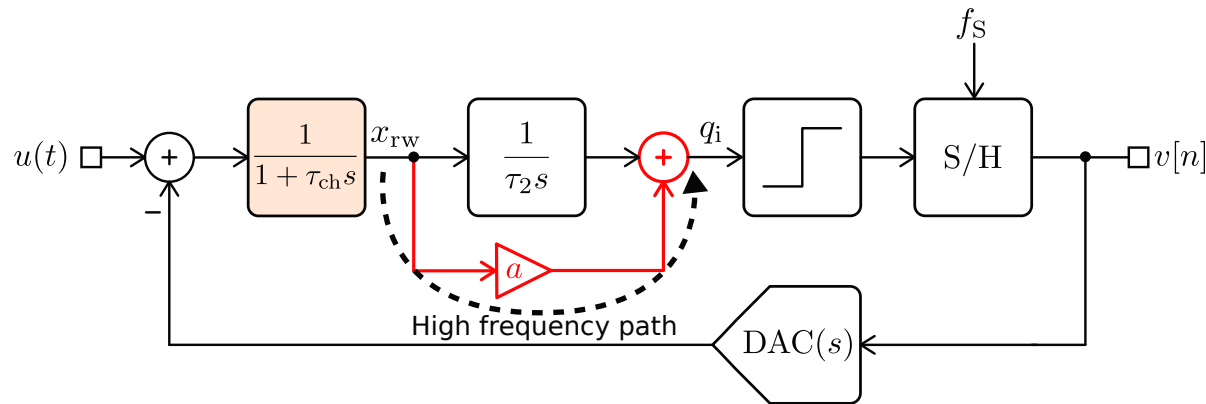
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- ▼ **f<sub>z</sub>** depends on sensor time constant **τ<sub>ch</sub>**
  - ↓τ<sub>ch</sub> → ↑f<sub>z</sub> **Leading to instability!!**
- ▼ **Potentiostatic voltage** strongly influenced by the **sensor input signal**
  - **x<sub>rw</sub> = a<sub>fb</sub>**



# Stability compensation

## ► Feed-Forward Topology



## ► Loop Filter Zero frequency location

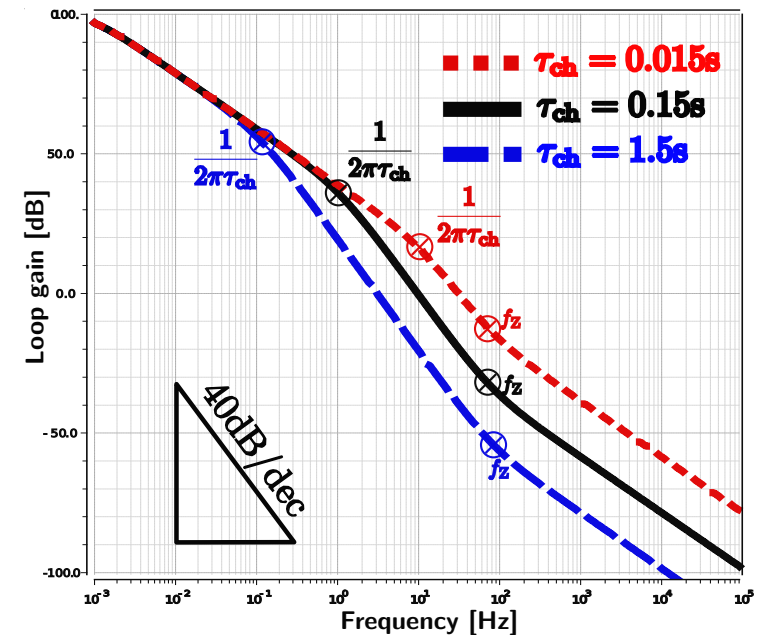
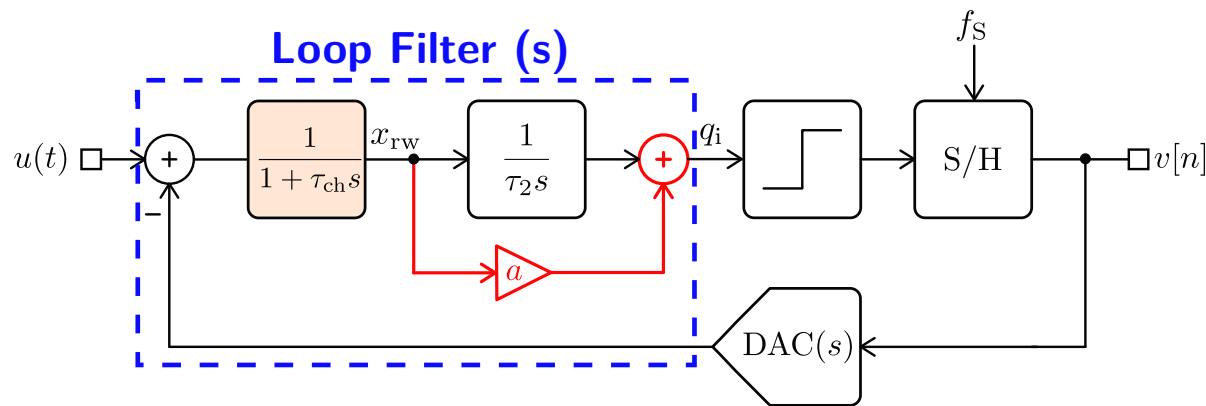
$$H_{FF}(s) = \frac{1 + a\tau_2 s}{(1 + \tau_{ch} s)\tau_2 s} ; \quad f_z = \frac{1}{2\pi a\tau_2}$$

- Variations in the sensor time constant do not compromise the stability of the system!



# Stability compensation

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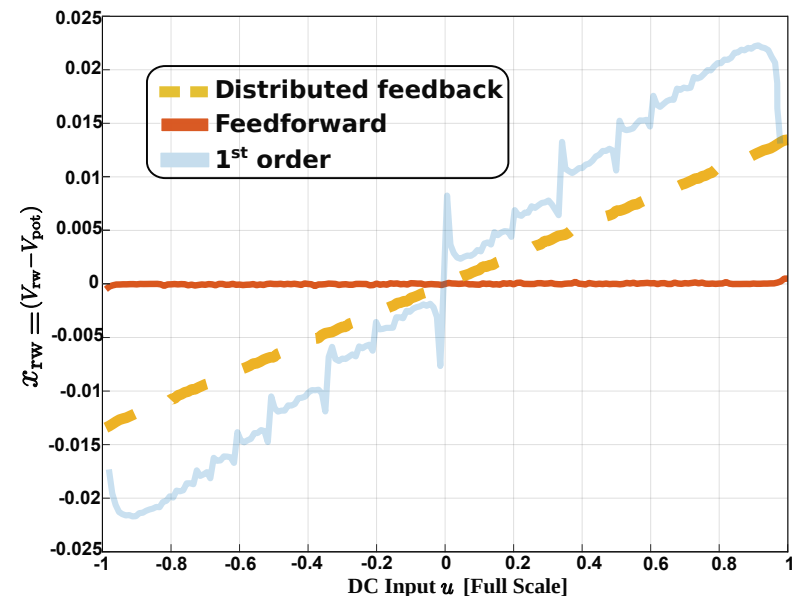


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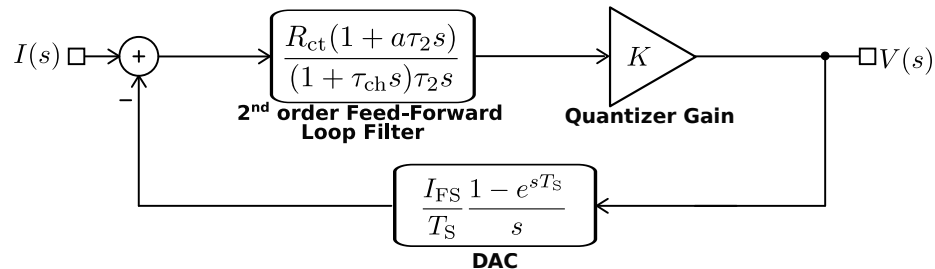
▲ Electronic integrator forces its input  $x_{rw}$  to have DC zero component.



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# Small-Signal Stability Analysis

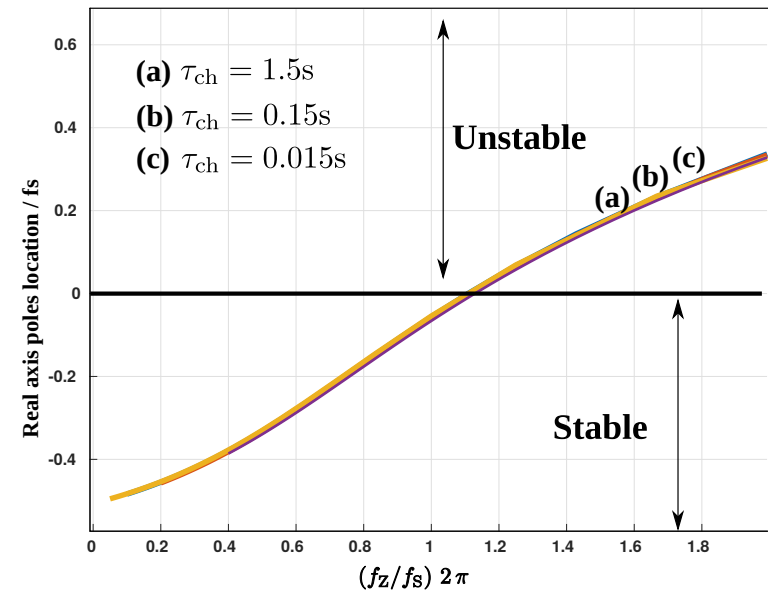
## ► Linear model



Linear model

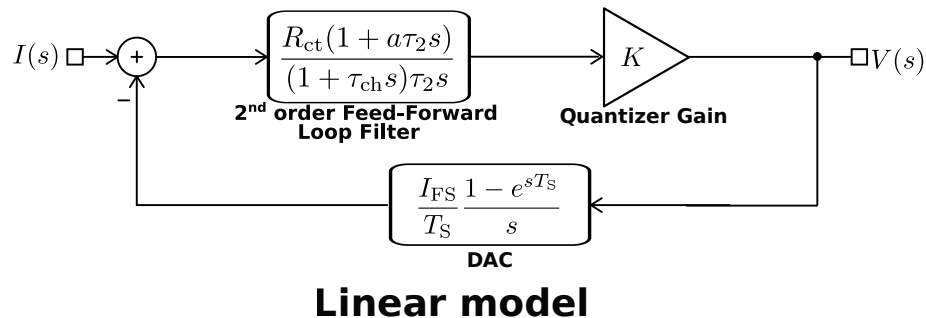
## ► Stability region as a function of $f_z/f_s$

- **Root locus** analysis: Closed-loop poles moves as quantizer gain changes
- **Stability condition:**  $f_z < f_s / (2\pi)$



# Small-Signal Stability Analysis

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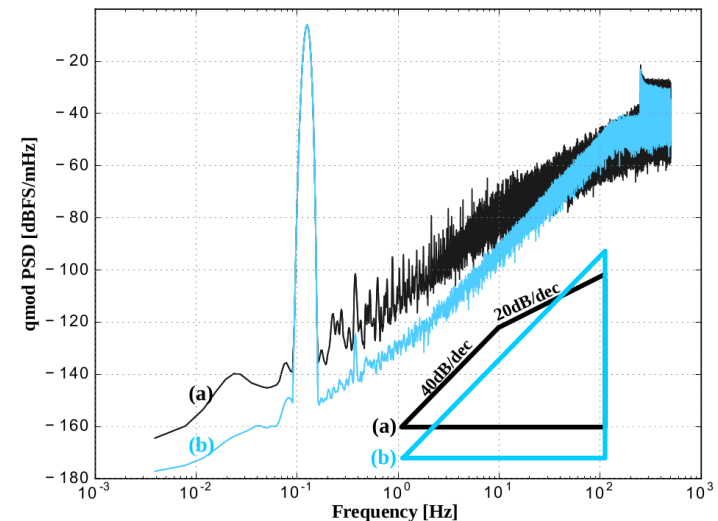
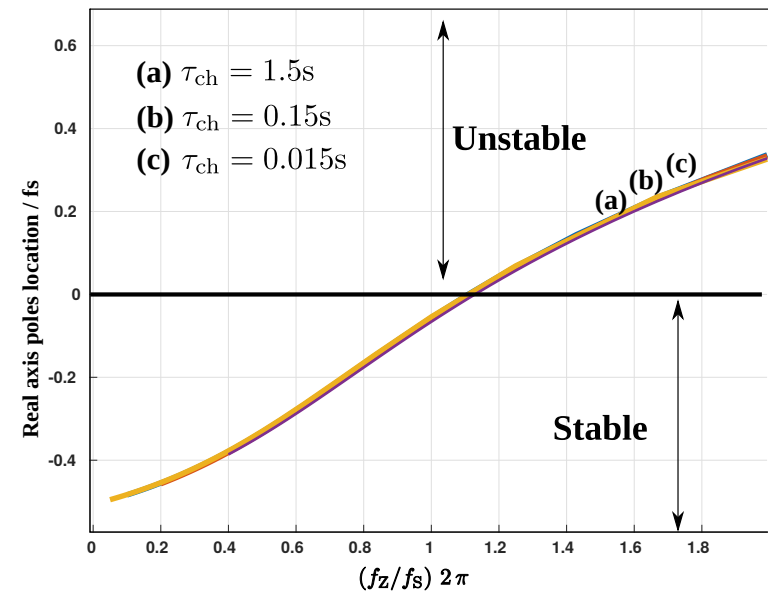


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## ► Power Spectrum as function of zero location

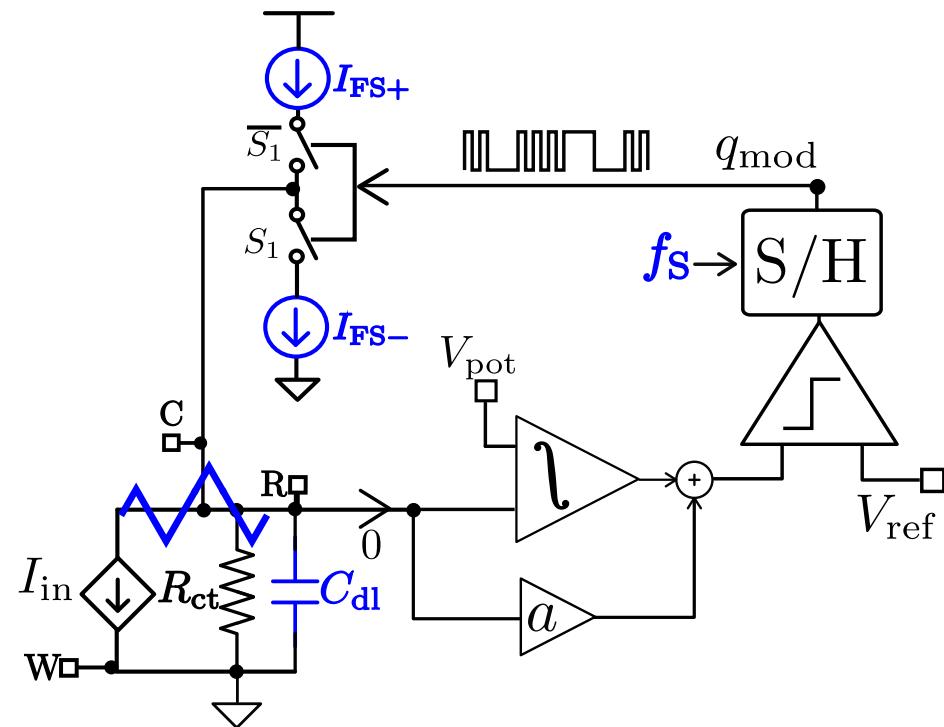
- **More stable** (More 1<sup>st</sup> order behaviour)  
**Less aggressive noise shaping**
- **Less safety stability margin**  
**Better noise shaping**



## Potentiostat Voltage Ripple

- Voltage ripple may be required to be kept below certain minimum
- Feedback current DAC ( $I_{FS}$ ) **charges/discharges  $C_{dl}$**
- $T_S$  is the only degree of freedom to **minimize ripple**
  - ( $C_{dl}$  and  $I_{FS}$  are fixed by the application)

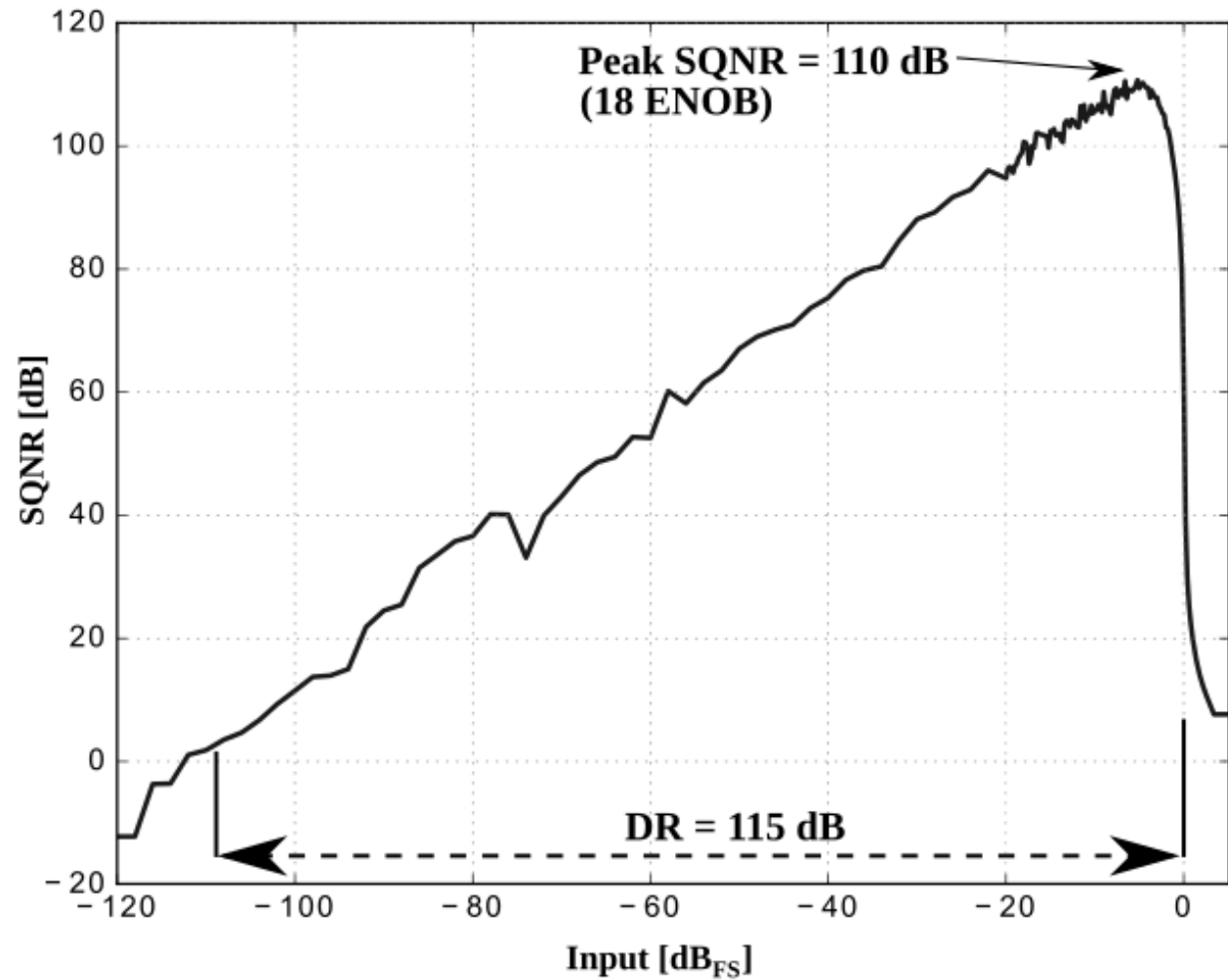
$$\frac{\Delta V_{rw}}{V_{rw}} \propto \frac{I_{FS} T_S / C_{dl}}{I_{FS} R_{ct}} = \frac{T_S}{\tau_1}$$



## SQNR vs input signal

### ► Top-level simulation

- $f_S = 1\text{kHz}$
- $\tau_{\text{ch}} = 0.15\text{s} (\text{OSR} \approx 500)$
- $f_Z/f_S = 1/(4\pi)$
- $I_{\text{FS}} = 2\mu\text{A}$





## Simulation Results

### ► Performance simulation results

- Power consumption mainly determined by current DAC FS

$$P_{\text{DAC}} = 4.7 \mu\text{W}$$

- Rest of circuit blocks

$$P = 370 \text{ nW}$$

### ► Cyclic Voltammetry

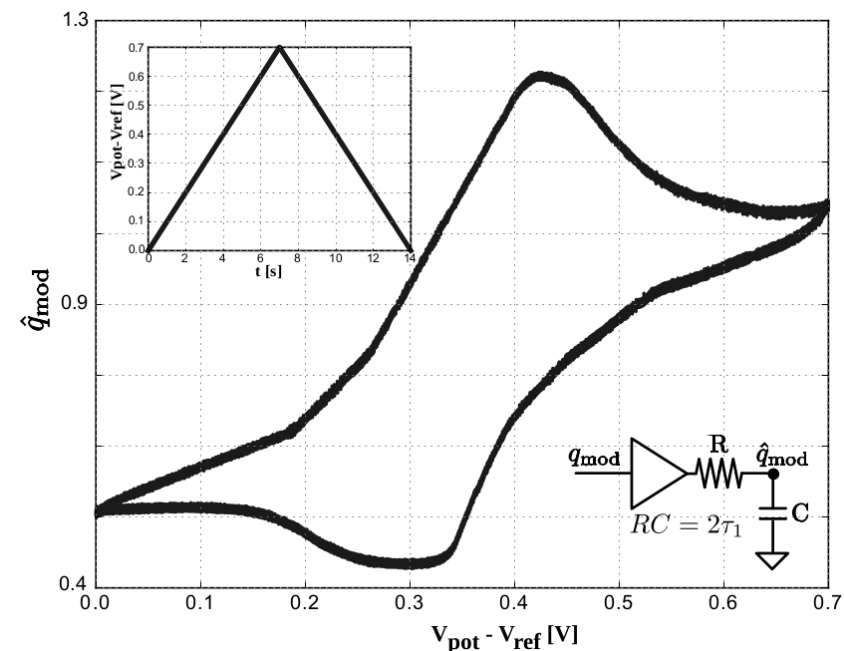
- Method for studying electrochemical reactions

- Triangular waveform is applied to the Reference-electrode, while the sensor current is measured simultaneously.

- **VerilogA** model

### 0.18 $\mu\text{m}$ CMOS technology

Parameter	Symbol	Value	Unit
Supply voltage	$V_{\text{DD}}$	1.8	V
Potential range	$V_{\text{pot}} - V_{\text{ref}}$	$\pm 0.7$	V
Input full scale	$I_{\text{FS}}$	$\pm 2$	$\mu\text{A}$
Oversampling ratio	OSR	500	–
Sampling frequency	$f_{\text{S}}$	1	kHz
Loop-filer zero location	$f_{\text{Z}}/f_{\text{S}}$	$1/\pi$	–
Potentiostatic ripple	$\Delta V_{\text{rw}}$	11.6	mV <sub>rms</sub>
Power at $2\mu\text{A}_{\text{FS}}$	$P_{\text{D}}$	5.1	$\mu\text{W}$



Ferrocyanide Cyclic Voltammetry



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## Conclusions

- ▶ **Compact architecture** thanks to the electrode-electrolyte interface used as an integrator stage in the  $\Delta\Sigma$  structure
- ▶ **Minimalist** analog circuits fully integrable in purely digital CMOS technologies
- ▶ **High resolution** with kHz-range clock frequencies:  $SQNR = 110\text{dB} @ 1\text{kHz}$
- ▶ **Ultra low-power (370nW)** operation compared to sensor consumption

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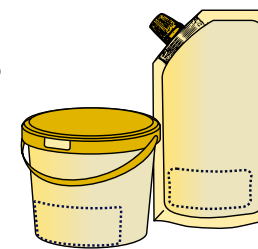
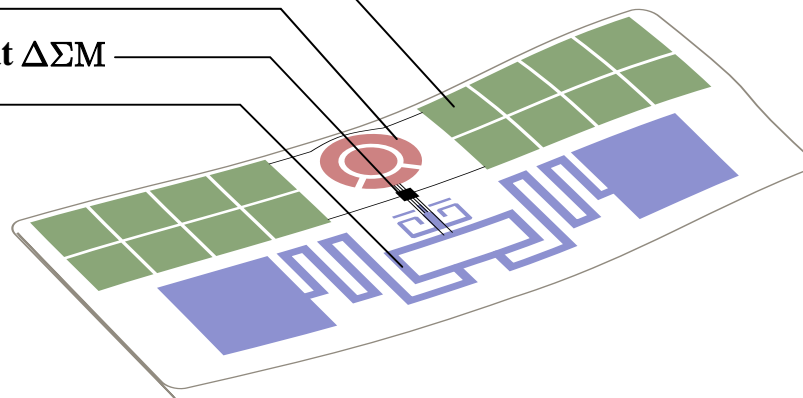
## Future work

Energy storage

Electrochemical sensor

<1mm<sup>2</sup> ASIC: Potentiostat  $\Delta\Sigma$

RF antennas



Smart tags for  
food quality control



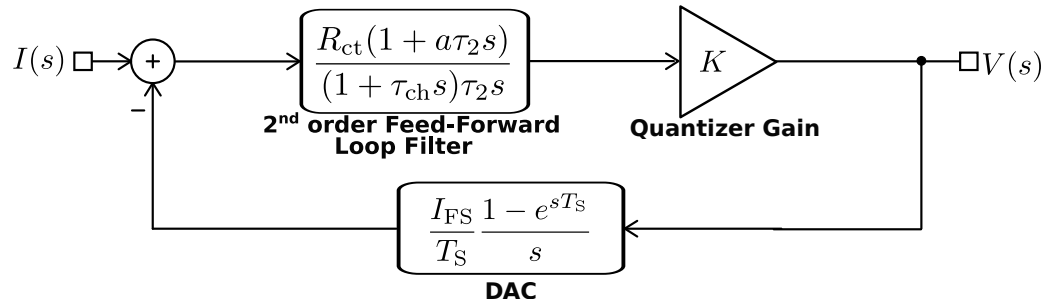
Wireless contact lens  
for health monitoring

# Power Consumption Comparison

	0.18 μm	0.5 μm	0.13 μm	0.18 μm	2.5 μm	<b>[This work]</b> 0.18 μm
<b>Technology</b>	0.18 μm	0.5 μm	0.13 μm	0.18 μm	2.5 μm	0.18 μm
<b>ADC structure</b>	Current to frequency	Delta-sigma	Single-Slope	Delta-sigma	Delta-sigma	Delta-sigma
<b>Sampling frequency</b>	-	100 kHz	1.25 kHz	-	1 kHz	1 kHz
<b>FS current</b>	<b>150 nA</b>	<b>16 μA</b>	<b>600 nA</b>	<b>1.65 μA</b>	<b>2 μA</b>	<b>2 μA</b>
<b>Power consumption @ supply voltage</b>	<b>3 μW @ 1.2 V</b>	<b>241 μW @ 1.2 V</b>	<b>56 μW @ 2 V</b>	<b>920 μW @ 1.8 V</b>	<b>25 μW @ 5 V</b>	<b>5 μW @ 1.8 V</b>

# Small-Signal Stability Analysis

## Linear model



Linear model

## Root Locus

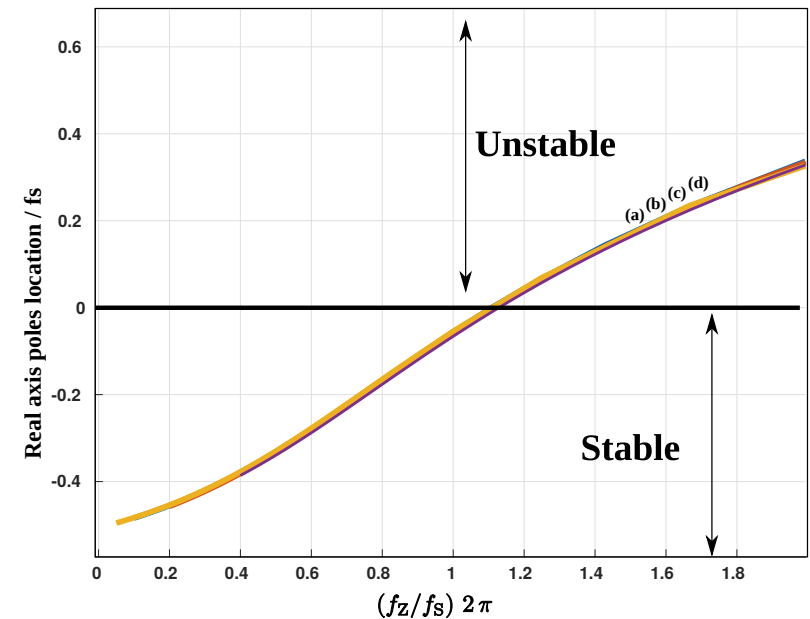
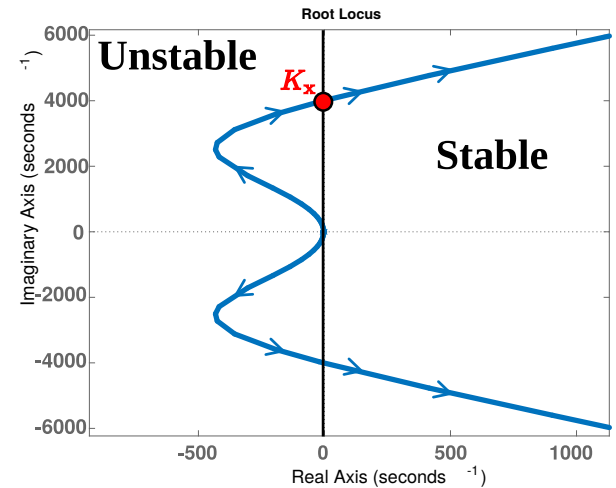
- Stability region as a function of **K**
- Worst-case scenario when **K** is maximum

## From stable situation

- Sweep input: 0 to FS to find maximum quantizer gain **K<sub>max</sub>** (worst-case)

## Stability region as a function of **f<sub>Z</sub>/f<sub>S</sub>**

- Sweep **f<sub>S</sub>/f<sub>Z</sub>** and check if **K<sub>max</sub>** is within the stable region



## Stability is ensured if:

$$\frac{f_Z}{f_S} < \frac{1}{2\pi}$$