# A 0.35µm 1.25V Piezo-Resistance Digital ROIC for Liquid Dispensing MEMS

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- 2 Input Gain Balancing
- 3 Differential Pre-Amplification
- 4 Integrating A/D Conversion
- 5 CMOS Integration





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#### **Bioplume Scenario**

- Liquid dispensing MEMS for µdroplet patterning
- Integrated piezo-resistive stress sensor to control positioning
- Dummy-based differential reading to cancel T/M/E disturbing signals
- Multi channel digital ROIC
- Low-power to prevent drying
- Low-voltage for single cell battery operation





# Integrated piezo-resistance

- Nominal value: 5KΩ to 10KΩ 100% (±20%)
- Quasi-static stress signal (9bit): ±0.0004%...±0.1%
- Technology mismatching: ±2%
- Dynamic disturbing signals: ±1%
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 $\pm 0.02\%$  (50LSB) dynamic residual!



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#### Gain Balancing Strategy

- Maximum gain compensation: ±2%
- ▶ Gain accuracy: ±0.0002%/2%=±0.01%
- Gain dynamic range: 2%/0.01%=(8+1)bit
- Residual dynamic disturbing: ±0.25LSB
- Residual DC: ±25LSB compensated by digital post-processing



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#### **ROIC** Architecture

- Parallel processing to reduce noise bandwidth
- Overall programmable sensitivity (*I<sub>com</sub>*)
- Differential gain
   balancing through sensor
   bias (\Delta I\_{com})
- OTA pre-amplification
- Integrating A/D conversion
- Digital only read-out/program-in
- Independent references to avoid crosstalk





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- ► Calibration through DAC: △I<sub>com</sub>(C<sub>8-0</sub>)
- Gate tuning:

$$\Delta V_{tun} = \frac{C_2}{C_1 + C_2} (V_{prog} - \frac{V_{DD}}{2})$$

- Compensation of piezo mismatch + OTA unbalance
- Repeated before every acquisition
- Design parameters: C<sub>1</sub>=9pF, C<sub>2</sub>=0.5pF





- **Differential Pre-Amplification** 3



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Differential V to single ended I

$$I_{eff} = G_m \left( V_{sens} - V_{ref} \right)$$

- Equivalent input low-noise
- Large diff. gain (in subthreshold):

$$G_m = \frac{I_{biasn}}{nU_t}$$

- High common rejection ratio
- Design parameters:  $I_{biasp,n} = 56\mu A, 44\mu A$



 $DR(V_{sens}) \sim 1 \text{mV}/4\mu \text{V}$  $(R_{sens} \sim 5 \text{k}\Omega \text{ and } I_{com} \sim 200 \mu \text{A})$ 

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$$V_{neq}\simeq 2\mu {\rm V_{rms}}~{\rm up}~{\rm to}~1{\rm kHz}$$
  $(\,V_{nres}\sim 0.4\mu {\rm V_{rms}}~{\rm for}~R_{sens}=10{\rm k}\Omega)$ 



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 $G_m \geq 0.8 {\rm mS}$   $DR(I_{e\!f\!f}) \sim 1 \mu {\rm A}/4 {\rm nA}$ 

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Differential V to single ended I

$$\frac{1}{CMRR} = \frac{\Delta G_m}{G_m} \left( 1 - \frac{1}{1 + \frac{1}{2nG_m R_{tail}}} \right)$$
$$CMRR \to \infty \text{ for } \Delta G_m \to 0 \text{ or } R_{tail} \to \infty$$

 $I_{eff} = G_m \left( V_{sens} - V_{ref} \right)$ MOSFET mismatching  $+ I_{biasn}$  finite impedance 10 Equivalent input low-noise 8 Large diff. gain (in subthreshold):

$$G_m = \frac{I_{biasn}}{nU_t}$$

- High common rejection ratio
- Design parameters:  $I_{biasp.n} = 56\mu A, 44\mu A$





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A/D Conversion

- Spike counting:
   PDM+digital filter
- CDS for low-frequency noise suppression
- ► Low-voltage switching ⇒ large reset times
- Design parameters:  $C_{int} = 4 p F$ ,  $V_{th} = 312 m V$
- X Classic PDM: reset-time **non-linearity**



Upper range saturation of the A/D curve!

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### A/D Conversion

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- CDS for low-frequency noise suppression
- ► Low-voltage switching ⇒ large reset times
- Design parameters: C<sub>int</sub> = 4pF, V<sub>th</sub> = 312mV
- New insensitive PDM



$$\mathbf{S}_{11\text{-}0} = \pm \frac{I_{eff} T_{int}}{C_{int} V_{th}} = \pm \frac{G_m T_{int}}{C_{int} V_{th}} I_{com} \left[ R_{sens} \left( 1 \pm \frac{\Delta I_{com}}{I_{com}} \right) - R_{ref} \right]$$



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Low-Voltage CMOS Blocks

#### Compact CTIA with CDS





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#### Low-Voltage CMOS Blocks

#### Compact CTIA with CDS

Class-AB window comparator





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Balancing Preamp ADC C

#### Low-Voltage CMOS Blocks

- Compact CTIA with CDS
- Class-AB window comparator
- Modular and floating threshold generator

$$\Delta V_{th} = U_t \ln \left[ \frac{(W/L)_B}{(W/L)_A} \left( 1 + \frac{I_B}{I_A} \right) + 1 \right]$$

- MA : weak inversion conduction
- MB : weak inversion saturation





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#### **ROIC Integration**





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#### **ROIC Integration**





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#### Results

- MEMS + ROIC integration not completed yet...
- Meanwhile, results from post-layout simulation
- 4 channel power supply: 1.5mW at 1.25V



Ideally:

$$\left|\frac{\mathbf{S}_{11\text{-}0}}{\Delta R_{sens}/R_{sens}}\right| = \frac{G_m T_{int}}{C_{int} V_{th}} I_{com} R_{sens} \equiv \frac{0.8 \text{mS} \times 1 \text{ms}}{4 \text{pF} \times 312 \text{mV}} \times 189 \mu \text{A} \times 5 k\Omega \simeq 6 \text{kLSB} / \%$$

 $V_{th}$  PTAT and  $G_m$  1/PTAT. If  $I_{com, bias}$  **PTAT**  $\Rightarrow$   $S_{11-0} \neq f(T)$ 



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#### Conclusions

- Quad-channel ROIC for integrated piezo-resistive sensors.
- Sensor balancing by digital gain tuning.
- Robust built-in A/D conversion.
- Low-voltage and low-power CMOS circuit realization.
- Integration in 0.35µm 2-poly 4-metal technology.
- Post-layout electrical simulation results.



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